APPLICANT(S):

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AMENDMENTS TO THE CLAIMS

What is claimed is:

1. (Original) A receiver comprising:

a direction metric determiner which generates direction metrics of each of a set of

possible directions of joint movement of at least two fingers of a finger block;

a metric selector which selects one of said direction metrics according to a

predetermined criterion; and

a finger adjuster which moves the fingers of said finger block in the directions

indicated by said selected direction metric.

2. (Original) A receiver according to claim 1, wherein said selected direction metric

is the maximal direction metric.

3. (Original) A receiver according to claim 1, wherein said finger adjuster moves the

fingers of said finger block only if said selected direction metric is the maximal

direction metric and exceeds a comparison direction metric by at least a

predetermined threshold.

4. (Original) A receiver according to claim 1, wherein said finger adjuster includes a

redefiner which redefines finger blocks once said fingers have been moved.

5. (Original) A receiver according to claim 1, wherein said finger block is formed of

two fingers.

6. (Original) A receiver according to claim 5, wherein said determiner generates said

direction metrics for five different directions of joint movement.

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7. (Original) A receiver according to claim 5, wherein said determiner generates said

direction metrics for six different directions of joint movement.

8. (Original) A receiver according to claim 5, wherein said determiner generates said

direction metrics for nine different directions of joint movement.

9. (Original) A receiver according to claim 1, wherein said finger block is formed of

two closely spaced fingers.

10. (Original) A receiver according to claim 9, wherein said closely spaced fingers

are 7/8 chip apart.

11. A receiver according to claim 1, wherein said finger block is formed of three

fingers.

12. (Original) A receiver according to claim 1, wherein delays between fingers are

set to be no smaller than 7/8 chip.

13. (Original) A receiver according to claim 1, wherein said direction metrics are

based on power estimation.

14. (Currently Amended) An article comprising a storage medium having stored

thereon instructions, that, when executed by a computing platform, cause the computing

platform to generate a direction metrics of each of a set of possible directions of joint

movement of at least to two fingers of a finger block, select one of said direction metrics

according to a predetermined criterion, and to move the fingers of said finger block in the

directions indicated by said selected direction metric.

15. (Original) The article according to claim 14, wherein said selected direction

metric is the maximal direction metric.

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16. (Original) The article according to claim 15, wherein the fingers of said finger

block is adjusted only if said selected direction metric is the maximal direction metric

and exceeds a comparison direction metric by at least a predetermined threshold.

17. (Original) The article according to claim 14, further having stored instructions

which cause the computing platform to redefine the finger blocks.

18. (Original) The article according to claim 14, wherein said finger block is formed

of two fingers.

19. (Original) The article according to claim 18, wherein said direction metrics are

generated for five different directions of joint movement.

20. The article according to claim 18, wherein said direction metrics are generated

for six different directions of joint movement.

21. (Original) The article according to claim 18, wherein said direction metrics are

generated for nine different directions of joint movement.

22. (Original) The article according to claim 14, wherein said finger block is formed

of two closely spaced fingers.

23. (Original) The article according to claim 22, wherein said closely spaced fingers

are 7/8 chip apart.

24. (Original) The article according to claim 14, wherein said finger block is formed

of three fingers.

25. (Original) The article according to claim 14, wherein delays between fingers are

set to be no smaller than 7/8 chip.

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26. (Original) The article according to claim 14, wherein said step of generating

includes the step of time averaging said direction metrics by summing consecutive

direction metrics.

27. (Original) The article according to claim 26, wherein said step of time averaging

uses a forgetting factor.

28. (Original) The article according to claim 14, wherein said direction metrics are

based on power estimation.

29. (Cancelled)

30. (Currently Amended) A method according to claim 29, wherein the step of

jointly tracking comprises the steps of comprising:

forming a finger block of at least two fingers; and

jointly tracking the fingers of said finger block by:

generating direction metrics of each of a set of possible directions of joint

movement of the fingers of said finger block;

selecting one of said direction metrics according to a predetermined criterion; and

moving the fingers of said finger block in the directions indicated by said selected

direction metric.